

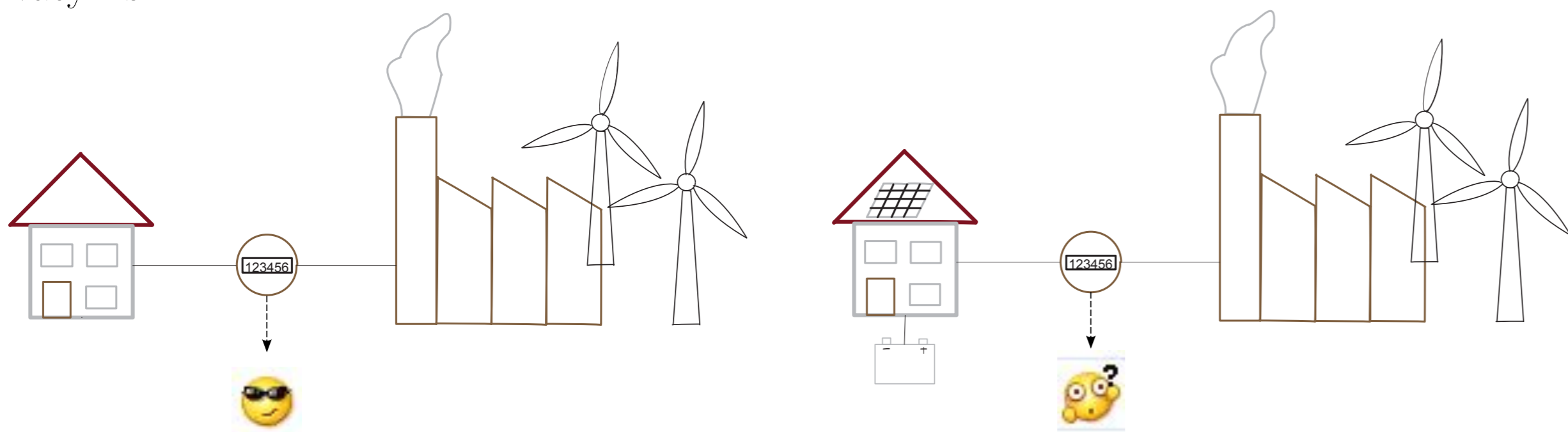
1 Motivation

Smart grid

- Monitor the grid more granularly.
- Predicate demand; detect failure; and adapt pricing.
- A more adaptive, reliable, and efficient grid

Smart meter

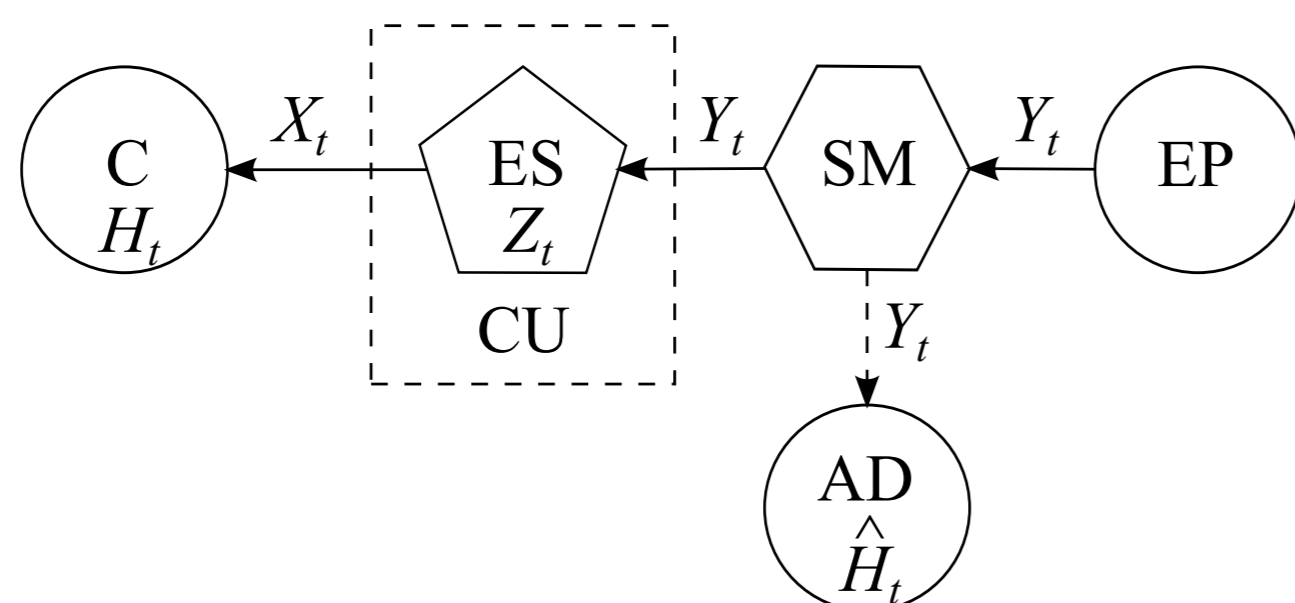
- Utility
- Privacy risk



State of arts

- Encryption
 - Do not work in the case of having inner threats.
- Distortion
 - Distort the energy supply from energy demand profile.
 - Use alternative energy sources or energy storage devices.
 - Information theoretic objective to maximize adversary uncertainty about the energy demand profile [1, 2, 3, 4, 6, 7]
 - Online algorithm to flatten smart meter readings [5]
 - Belief state MDP formulation [6, 7, 9]
 - Detection theoretic objectives [8, 9]

2 Belief State MDP Formulation



Settings

- Control strategy: $p_{Y_t|X_t, Z_t}$ under a constraint $z_t - z_{t+1} + y_t = x_t$
- Markov property:

$$P_{H_{t+1}, X_{t+1}, Z_{t+1}, Y_{t+1}|H^t, X^t, Z^t, Y^t} = P_{Y_{t+1}|X_{t+1}, Z_{t+1}} \cdot P_{X_{t+1}|H_{t+1}, X_t} \cdot P_{Z_{t+1}|X_t, Z_t} \cdot P_{H_{t+1}|H_t}$$

- Instantaneous privacy leakage:

$$r_t = \sum_{y_t} \left\{ \min_{\hat{h}_t} \sum_{h_t, x_t, z_t} c(\hat{h}_t, h_t) p_{Y_t|X_t, Z_t}(y_t|x_t, z_t) p_{H_t, X_t, Z_t}(h_t, x_t, z_t) \right\}$$

- Informed and greedy adversary
- Bayesian detection model of adversary behavior

Belief state MDP elements

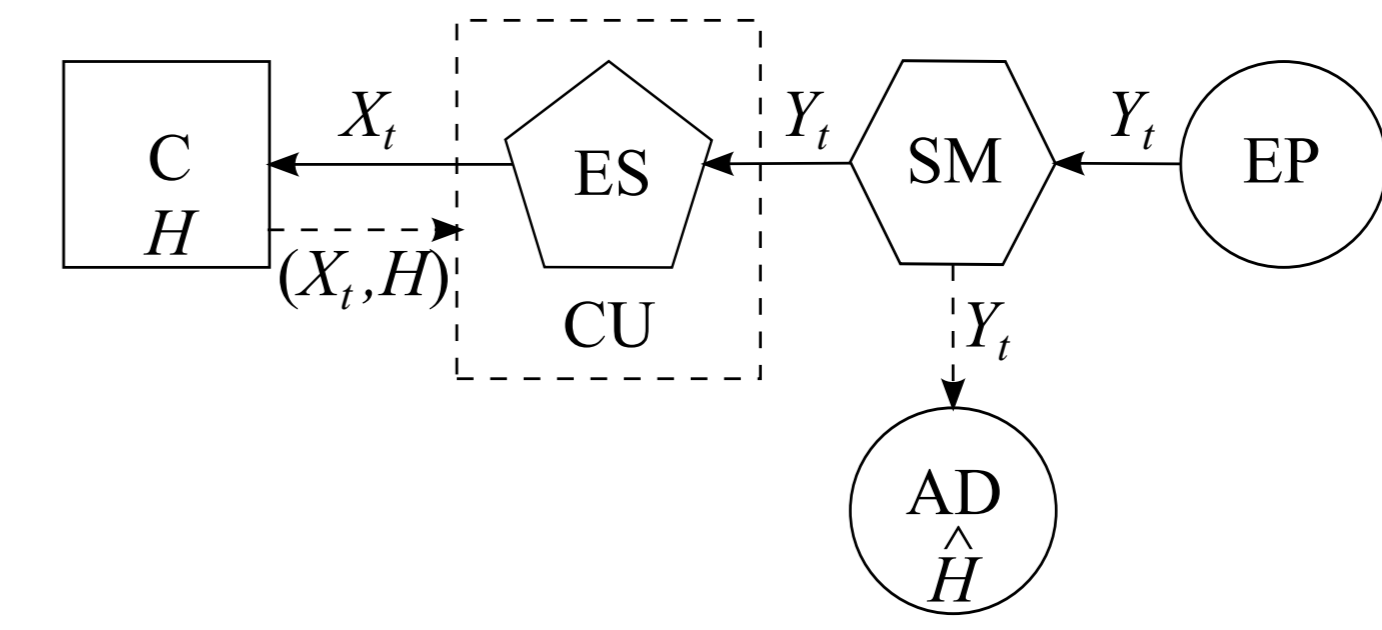
- State: $s_t = (h_t, x_t, z_t)$
- Belief state: $b_t = p_{H_t, X_t, Z_t}$
- Action: $a_t = p_{Y_t|X_t, Z_t}$
- Reward: $r_t(b_t, a_t)$
- Policy: $\delta_t : b_t \rightarrow a_t$
- Belief state transition: $Pr(b_{t+1}|b_t, a_t)$

On observing (calculating) the belief state b_t , a_t is determined based on δ_t . Then, the next belief state b_{t+1} can be calculated (observed) and the reward r_t can be determined.

A privacy-preserving control design in belief state MDP formulation

- Let $\Delta = \{\delta_0, \delta_1, \dots\}$.
- Let $V = \sum_{t=0}^{\infty} \beta^t r_t$ where $0 \leq \beta < 1$.
- A privacy-preserving objective: Optimize Δ to maximize V .
- Bellman equation: $V(\Delta^*, b_t) = \max_{a_t} \{r_t(b_t, a_t) + \beta V(\Delta^*, b_{t+1})\}$
 - If the solution exists, there is a stationary optimal policy, i.e., $\delta_t^* = \delta^*$.
 - $\delta^* : b_t \rightarrow a_t^*$
 - Established computational methods

3 Use an Infinite-Capacity Energy Storage Device



Settings

- Binary hypothesis
- “Ideal” infinite-capacity energy storage device
 - Instantaneous demand x_t is always satisfied.
 - Asymptotic balance: $\lim_{n \rightarrow \infty} \sum_{t=1}^n (x_t - y_t) = 0, \forall h$
 - Law of large numbers leads to average energy supply constraints:

$$E(Y|H = h_0) = f_0; E(Y|H = h_1) = f_1.$$

- Control strategy: $p_{Y_t|X_t, H}$
- Markov property:

$$P_{X_{t+1}, Y_{t+1}|X^t, Y^t, H} = P_{Y_{t+1}|X_{t+1}, H} \cdot P_{X_{t+1}|H}$$

- Assumptions on the adversary
 - Informed and greedy adversary
 - Neyman-Pearson hypothesis testing model of adversary behavior:

$$p_{\hat{H}|H}^{\min}(h_0|h_1) = \min p_{\hat{H}|H}(h_0|h_1), \text{ s.t. } p_{\hat{H}|H}(h_1|h_0) \leq \phi$$

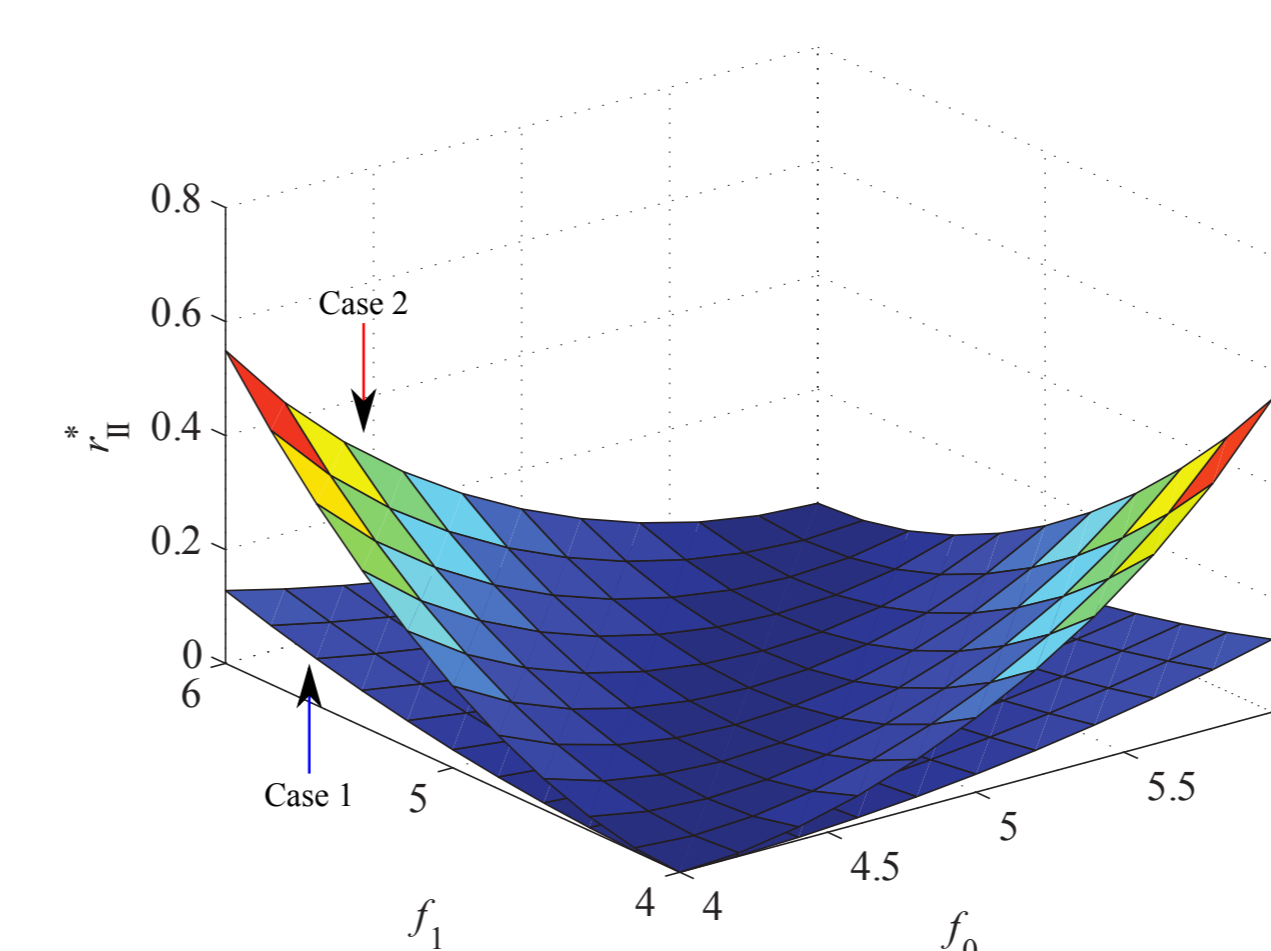
Asymptotic measure of privacy leakage risk

- Chernoff-Stein Lemma: The Kullback-Leibler divergence $D(p_{Y|H=h_0} || p_{Y|H=h_1})$ is the asymptotic exponential decay rate of $p_{\hat{H}|H}^{\min}(h_0|h_1)$.
- Privacy leakage metric: $r_{\text{II}}^* = D(p_{Y|H=h_0} || p_{Y|H=h_1})$
 - Reducing r_{II}^* means that the adversary needs more observations to achieve a certain value of $p_{\hat{H}|H}^{\min}(h_0|h_1)$ from an asymptotic perspective.

Optimal privacy-preserving control design

- Optimize $p_{Y_t|X_t, H}$ to minimize r_{II}^* and to satisfy average energy supply constraints.
- Results about $p_{Y_t|X_t, H}^*$:
 - Energy control depends on H only such that $p_{Y_t|X_t, H}^*$ is a constant given (y_t, h) .
 - $|\mathcal{Y}^*| \leq 2$.
 - If $|\mathcal{Y}^*| = 2$, $\mathcal{Y}^* = \{y_{\min}, y_{\max}\}$.

Numerical illustration



- Assumptions:
 - $f_0, f_1 \in [4, 6]$
 - Case 1: $y_{\min} = 1, y_{\max} = 9$
 - Case 2: $y_{\min} = 3, y_{\max} = 7$
- Two ways to suppress the privacy risk:
 - Increase the difference $y_{\max} - y_{\min}$.
 - Decrease the difference $|f_0 - f_1|$.

References

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